# NAG Fortran Library Routine Document

## F04ASF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

### **1** Purpose

F04ASF calculates the accurate solution of a set of real symmetric positive-definite linear equations with a single right-hand side, Ax = b, using a Cholesky factorization and iterative refinement.

### 2 Specification

 SUBROUTINE F04ASF(A, IA, B, N, C, WK1, WK2, IFAIL)

 INTEGER
 IA, N, IFAIL

 real
 A(IA,\*), B(\*), C(\*), WK1(\*), WK2(\*)

### **3** Description

Given a set of real linear equations Ax = b, where A is a symmetric positive-definite matrix, the routine first computes a Cholesky factorization of A as  $A = LL^T$  where L is lower triangular. An approximation to x is found by forward and backward substitution. The residual vector r = b - Ax is then calculated using *additional precision* and a correction d to x is found by solving  $LL^Td = r$ . x is then replaced by x + d, and this iterative refinement of the solution is repeated until machine accuracy is obtained.

### 4 References

Wilkinson J H and Reinsch C (1971) Handbook for Automatic Computation II, Linear Algebra Springer-Verlag

### **5** Parameters

1: A(IA,\*) - real array

Note: the second dimension of the array A must be at least max(1, N).

On entry: the upper triangle of the n by n positive-definite symmetric matrix A. The elements of the array below the diagonal need not be set.

On exit: the elements of the array below the diagonal are overwritten; the upper triangle of A is unchanged.

2: IA – INTEGER

On entry: the first dimension of the array A as declared in the (sub)program from which F04ASF is called.

*Constraint*: IA  $\geq \max(1, N)$ .

3: B(\*) - real array

Note: the dimension of the array B must be at least max(1,N) .

On entry: the right-hand side vector b.

4: N – INTEGER

On entry: n, the order of the matrix A. Constraint:  $N \ge 0$ . Input/Output

Input

Input

Input

Output

Workspace

Input/Output

#### 5: C(\*) – *real* array

**Note:** the dimension of the array C must be at least max(1, N). On exit: the solution vector x.

6: WK1(\*) - *real* array *Workspace* Note: the dimension of the array WK1 must be at least max(1, N).

7: WK2(\*) – *real* array

Note: the dimension of the array WK2 must be at least max(1, N).

8: IFAIL – INTEGER

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

### 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

The matrix A is not positive-definite, possibly due to rounding errors.

IFAIL = 2

Iterative refinement fails to improve the solution, i.e., the matrix A is too ill-conditioned.

IFAIL = 3

 $\begin{array}{ll} \text{On entry,} & N < 0, \\ \text{or} & IA < max(1,N). \end{array}$ 

### 7 Accuracy

The computed solutions should be correct to full machine accuracy. For a detailed error analysis see page 39 of Wilkinson and Reinsch (1971).

### 8 Further Comments

The time taken by the routine is approximately proportional to  $n^3$ .

The routine must not be called with the same name for parameters B and C.

To solve the set of linear equations Ax = b where

$$A = \begin{pmatrix} 5 & 7 & 6 & 5 \\ 7 & 10 & 8 & 7 \\ 6 & 8 & 10 & 9 \\ 5 & 7 & 9 & 10 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} 23 \\ 32 \\ 33 \\ 31 \end{pmatrix}$$

#### 9.1 Program Text

**Note:** the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
F04ASF Example Program Text
*
*
      Mark 15 Revised. NAG Copyright 1991.
*
      .. Parameters ..
      INTEGER
                        NMAX, IA
      PARAMETER
                        (NMAX=8, IA=NMAX)
      INTEGER
                        NIN, NOUT
      PARAMETER
                        (NIN=5, NOUT=6)
      .. Local Scalars ..
      INTEGER
                        I, IFAIL, J, N
      .. Local Arrays ..
*
      real
                        A(IA,NMAX), B(NMAX), C(NMAX), WK1(NMAX),
     +
                        WK2(NMAX)
*
      .. External Subroutines ..
      EXTERNAL
                       F04ASF
*
      .. Executable Statements ..
      WRITE (NOUT, *) 'F04ASF Example Program Results'
      Skip heading in data Ûle
      READ (NIN,*)
      READ (NIN,*) N
      WRITE (NOUT, *)
      IF (N.GE.O .AND. N.LE.NMAX) THEN
         READ (NIN,*) ((A(I,J),J=1,N),I=1,N), (B(I),I=1,N)
         IFAIL = 0
*
         CALL F04ASF(A, IA, B, N, C, WK1, WK2, IFAIL)
*
         WRITE (NOUT, *) ' Solution'
         WRITE (NOUT,99998) (C(I),I=1,N)
      ELSE
         WRITE (NOUT,99999) 'N is out of range: N = ', N
      END IF
      STOP
*
99999 FORMAT (1X,A,I5)
99998 FORMAT (1X, F9.4)
      END
```

#### 9.2 Program Data

F04ASF Example Program Data 4 5 7 6 5 7 7 10 8 9 6 8 10 7 10 5 9 23 32 33 31

## 9.3 Program Results

F04ASF Example Program Results

Solution 1.0000 1.0000 1.0000 1.0000